



**AAI-003-001618**      Seat No. \_\_\_\_\_  
**B. Sc. (Sem. VI) (CBCS) Examination**  
**March / April - 2016**  
**BSMT-603(A) : Mathematics**  
*(Optimization & Numerical Analysis - II)*  
*(New Course)*

**Faculty Code : 003**  
**Subject Code : 001618**

Time :  $2\frac{1}{2}$  Hours]

[Total Marks : 70

- Instructions :** (1) Write answer of MCQs in your answer book only.  
(2) All questions are compulsory.  
(3) Figures to the right indicate full marks.

**1** Give answers of all following questions : **20**

- (1) Which of the following is two step method?  
(A) Picard's                      (B) Runge's  
(C) Trapezoidal                (D) Milne's
- (2) Using Lagrange's interpolation formula one can fit \_\_\_\_\_  
 $n$  degree polynomial from given  $n + 1$  set of observation.  
(A) almost                      (B) atleast  
(C) exactly                      (D) None of these
- (3) If  $A$  is solution produced using Runge-Kutta 2<sup>nd</sup> order  
and  $B$  is solution produced using improved Euler method  
then  
(A)  $A = B$   
(B)  $A$  is more accurate than  $B$   
(C)  $B$  is more accurate than  $A$   
(D) Cannot say

- (4) Which of the following method can be used to find root of transcendental equation.
- (A) Stirling's Interpolation  
(B) Divided difference Interpolation  
(C) Newton-Cotes quadrature method  
(D) Inverse Lagrange Interpolation
- (5) Minimum no of sub-intervals required to apply Simpson's 3/8 rule and Trapezoidal rule simultaneously is
- (A) 1 (B) 2  
(C) 3 (D) 6
- (6) Runge-Kutta 2<sup>nd</sup> order method is similar as
- (A) Euler method  
(B) Improved Euler method  
(C) Runge's method  
(D) None of these
- (7) Divided difference interpolation method applicable for given domain data with \_\_\_\_\_ length of subintervals.
- (A) common (B) uncommon  
(C) both (A) and (B) (D) none of these
- (8) If the value of  $p = \frac{x - x_0}{h}$  lies in  $\left[-\frac{1}{4}, 0\right]$ , the best suitable interpolation to apply is
- (A) Gauss-Backward (B) Gauss-forward  
(C) Bessell's (D) None of these
- (9) Picard's method can solve differential equation of the form :
- (A)  $y' = f(x, y)$   
(B)  $y' = f(x, y), y(x_0) = y_0$   
(C)  $y = f(x, y), y(x_0) = y_0$   
(D) None of these

- (10) Which of the following is an iterative method ?
- (A) Picard's method
  - (B) Taylor series method
  - (C) Trapezoidal
  - (D) Bessel's interpolation
- (11) Hungarian method is to get optimum solution of
- (A) LPP
  - (B) AP
  - (C) TP
  - (D) none
- (12) A transportation problem of  $n$  supply point and  $m$  demand point is having degenerate solution, when number of allocation in basic feasible solution is
- (A)  $= m + n - 1$
  - (B)  $< m + n - 1$
  - (C)  $> m + n - 1$
  - (D) Both (B) and (C)
- (13) Graphical method is useful to solve LPP, if LPP consist \_\_\_\_\_ decision variables
- (A) 2
  - (B) 3
  - (C) 4
  - (D) None
- (14) In context of transportation problem, LCM means
- (A) Least Common Multiple
  - (B) Least Cost Multiple
  - (C) Least Cost Method
  - (D) None of these
- (15) If the line segment joining every pair of points of set  $S$  lies in  $S$  then  $S$  is \_\_\_\_\_
- (A) convex set
  - (B) concave set
  - (C) both (A) and (B)
  - (D) can't say

- (16) Primal contains second variable unrestricted in sign, the corresponding dual has second
- (A) variable unrestricted in sign
  - (B) constraint of equality type
  - (C) variable negative
  - (D) constraint does not exist
- (17) If Simplex method produces a solution of LPP, the solution can not be
- (A) degenerate
  - (B) basic feasible
  - (C) feasible
  - (D) infeasible
- (18) For maximization LP problem, the simplex method is terminated when all values
- (A)  $C_j - Z_j \leq 0$
  - (B)  $C_j - Z_j \geq 0$
  - (C)  $C_j - Z_j = 0$
  - (D)  $Z_j \leq 0$
- (19) Which of the following method/s is/are use to find optimal solution for the given TP?
- (A) VAMP
  - (B) MODI method
  - (C) Both (A) and (B)
  - (D) None of the above
- (20) To balance the given unbalanced TP we add
- (A) one dummy row
  - (B) one dummy column
  - (C) both (A) and (B)
  - (D) either (A) or (B)

2 (a) Attempt any **three** :

6

(1) Derive first order derivative of Newton's-forward interpolation formula.

(2) If  $f(x) = x^{-1}$ , show that  $f(a, b, c, d) = \frac{1}{abcd}$ .

(3) Find  $\int_0^1 y dx$  using Simpson's  $\frac{1}{3}^{rd}$  rule from the

following table :

$x$	0	0.25	0.5	0.75	1
$y$	1.0000	0.9896	0.9589	0.9089	0.8415

(4) Write working rule of Runge's method.

(5) Write two difference between Gauss-Backward interpolation and Lagrange's interpolation.

(6) In usual notation prove that

$$D = \frac{1}{h} \left[ \Delta - \frac{\Delta^2}{2} + \frac{\Delta^3}{3} - \frac{\Delta^4}{4} + \dots \right]$$

(b) Attempt any **three** :

9

(1) Derive Newton's-forward interpolation formulae from divided difference interpolation formula.

(2) Solve  $y' = x + y$  with  $y(0) = 1$ , using Picard's method.

(3) Find  $y'$  at  $x = 0.04$  from given data below, using Bessel's interpolation formula :

$x$	0.01	0.02	0.03	0.04	0.05	0.06
$y$	0.1023	0.1047	0.1071	0.1096	0.1122	0.1148

(4) Derive stirling's interpolation formula.

(5) If  $y_0, y_1, \dots, y_6$  are the consecutive terms of a series, then using Lagrange's formula prove that

$$y_3 = 0.05(y_0 + y_6) - 0.3(y_1 + y_5) + 0.75(y_2 + y_4)$$

(6) Explain Improved Euler method graphically.

(c) Attempt any **two** : 10

- (1) Derive Lagrange's interpolation formula.
- (2) Derive Newton-Cote's quadrature formula and hence deduce Simpson's 3/8 rule.
- (3) Derive Milne-Thomson predictor-corrector formula.
- (4) Derive Laplace- Everett's interpolation formula.
- (5) Find  $y$  and  $z$  at  $x = 0.1$  using Runge-Kutta forth

order method, given that  $\frac{dy}{dx} = x + z$ ,  $\frac{dz}{dx} = x - y^2$ ,

$y(0) = 2$  and  $z(0) = 1$ .

3 (a) Attempt any **three** : 6

- (1) Define : (i) Decision variable (ii) Slack variable.
- (2) Write dual of Maximize  $Z = 2x + 3y$  subject to  $x - y \leq 3$ ,  $3x + 2y \leq 2$  and  $x, y \geq 0$ .
- (3) Explain canonical form of linear programming problem.
- (4) Solve the following transportation problem, using North-West Corner method :

	Destinations				Supply
	$D_1$	$D_2$	$D_3$	$D_4$	
Source $S_1$	19	30	50	10	7
$S_2$	70	30	40	6	9
$S_3$	40	8	70	20	18
Demand	5	8	7	14	34

- (5) Define unbalanced transportation problem with suitable example.
- (6) Define: (i) Convex hull (ii) Convex set

(b) Attempt any **three** :

9

- (1) Define feasible solution and basic feasible solution also write differences between them.
- (2) Define alternate optimality in linear programming problem with suitable example.
- (3) Describe Vogel's Approximation Method.
- (4) Explain primal-dual relationship for linear programming problem.
- (5) Solve the following LPP using graphical method

$$\text{Minimize } Z = 6000x_1 + 4000x_2$$

$$\text{Subject to } x_1 + x_2 \geq 24$$

$$x_1 + x_2 \geq 16$$

$$x_1 + 3x_2 \leq 24$$

$$x_1, x_2 \geq 0$$

- (6) Solve the following LPP using the simplex method and also find out two different optimal solution

$$\text{Maximize } Z = 2x + 3y$$

$$\text{Subject to condition } 4x + 6y \leq 24$$

$$x \leq 5;$$

$$x, y \geq 0$$

(c) Attempt any **two** :

10

- (1) Explain simplex algorithm.
- (2) Solve the following assignment problem

		<b>Machines</b>				
<b>Job</b>		$M_1$	$M_2$	$M_3$	$M_4$	$M_5$
	$J_1$	11	7	10	17	10
	$J_2$	13	21	7	11	13
	$J_3$	13	13	15	13	14
	$J_4$	18	10	13	16	14
	$J_5$	12	8	16	19	10

(3) Find optimum solution of transportation problem stated in question 3(A)(4).

(4) Find dual of linear programming problem

$$\text{Minimize } Z = 8x_1 + 5x_2 + 4x_3$$

$$\text{subject to } 4x_1 + 2x_2 + 8x_3 = 12$$

$$7x_1 + 5x_2 + 6x_3 \geq 9$$

$$8x_1 + 5x_2 + 4x_3 \leq 10$$

$$3x_1 + 7x_2 + 9x_3 \geq 7$$

$$x_1 \geq 0, x_2 \text{ unrestricted in sign, } x_3 \leq 0.$$

(5) Solve the following linear programming problem by Big-M method

$$\text{Maximize } Z = 2x_1 + x_2 + 3x_3$$

$$\text{Subject to } x_1 + x_2 + 2x_3 \leq 5$$

$$2x_1 + 3x_2 + 4x_3 = 12$$

$$x_1, x_2, x_3 \geq 0$$

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